



## Kinematics:

- **position:**  $\vec{r} = \int \vec{v} dt$
- **velocity:**  $\vec{v} = \frac{d\vec{r}}{dt} = \int \vec{a} dt$
- **acceleration:**  $\vec{a} = \frac{d\vec{v}}{dt} = \frac{d^2\vec{r}}{dt^2}$

**Dynamics:** cause and effect:  $\vec{F} = m\vec{a}$

**Modes of motion:** translation, rotation

**Conservation laws:** energy, momentum, angular momentum

**Effective forces:** elastic, contact, friction, ...

**Fundamental forces:** gravitational, electric, magnetic, ...