

Routhian Function [mln39]

Goal: systematic elimination of cyclic coordinates in the Lagrangian formulation of mechanics.

Consider a system with n generalized coordinates of which the first k are cyclic.

Lagrangian: $L(q_{k+1}, \dots, q_n, \dot{q}_1, \dots, \dot{q}_n, t) \Rightarrow q_1, \dots, q_k$ are cyclic.

Routhian: $R(q_{k+1}, \dots, q_n, \dot{q}_{k+1}, \dots, \dot{q}_n, \beta_1, \dots, \beta_k, t) = L - \sum_{i=1}^k \beta_i \dot{q}_i$.

where the relations $\beta_i = \frac{\partial L}{\partial \dot{q}_i} = \text{const}$, $i = 1, \dots, k$ are to be inverted into $\dot{q}_i = \dot{q}_i(q_{k+1}, \dots, q_n, \dot{q}_{k+1}, \dots, \dot{q}_n, \beta_1, \dots, \beta_k, t)$, $i = 1, \dots, k$.

Compare coefficients of the variations

$$\delta R = \sum_{i=k+1}^n \frac{\partial R}{\partial q_i} \delta q_i + \sum_{i=k+1}^n \frac{\partial R}{\partial \dot{q}_i} \delta \dot{q}_i + \sum_{i=1}^k \frac{\partial R}{\partial \beta_i} \delta \beta_i + \frac{\partial R}{\partial t} \delta t,$$

$$\delta \left(L - \sum_{i=1}^k \beta_i \dot{q}_i \right) = \sum_{i=k+1}^n \frac{\partial L}{\partial q_i} \delta q_i + \sum_{i=k+1}^n \frac{\partial L}{\partial \dot{q}_i} \delta \dot{q}_i - \sum_{i=1}^k \dot{q}_i \delta \beta_i + \frac{\partial L}{\partial t} \delta t.$$

Resulting relations between partial derivatives:

$$\frac{\partial R}{\partial q_i} = \frac{\partial L}{\partial q_i}, \quad \frac{\partial R}{\partial \dot{q}_i} = \frac{\partial L}{\partial \dot{q}_i}, \quad i = k+1, \dots, n,$$

$$\frac{\partial R}{\partial t} = \frac{\partial L}{\partial t}; \quad \dot{q}_i = -\frac{\partial R}{\partial \beta_i}, \quad i = 1, \dots, k.$$

Lagrange equations for the noncyclic coordinates:

$$\frac{\partial R}{\partial q_i} - \frac{d}{dt} \frac{\partial R}{\partial \dot{q}_i} = 0, \quad i = k+1, \dots, n.$$

Time evolution of cyclic coordinates:

$$\dot{q}_i(t) = - \int dt \frac{\partial R}{\partial \beta_i}, \quad i = 1, \dots, k.$$