

# Linearly Damped Harmonic Oscillator [mln6]

Equation of motion:  $m\ddot{x} = -kx - \gamma\dot{x} \Rightarrow \ddot{x} + 2\beta\dot{x} + \omega_0^2x = 0$ .

Damping parameter:  $\beta \equiv \gamma/2m$ ; characteristic frequency:  $\omega_0 = \sqrt{k/m}$ .

Ansatz:  $x(t) = e^{rt} \Rightarrow (r^2 + 2\beta r + \omega_0^2)e^{rt} = 0 \Rightarrow r_{\pm} = -\beta \pm \sqrt{\beta^2 - \omega_0^2}$ .

**Overdamped motion:**  $\Omega_1 \equiv \sqrt{\beta^2 - \omega_0^2} > 0$

Linearly independent solutions:  $e^{r_+t}, e^{r_-t}$ .

General solution:  $x(t) = (A_+e^{\Omega_1 t} + A_-e^{-\Omega_1 t})e^{-\beta t}$ .

Initial conditions:  $A_+ = (\dot{x}_0 - r_-x_0)/2\Omega_1, \quad A_- = (r_+x_0 - \dot{x}_0)/2\Omega_1$ .

**Critically damped motion:**  $\sqrt{\omega_0^2 - \beta^2} = 0, \quad r = -\beta$

Linearly independent solutions:  $e^{rt}, te^{rt}$ .

General solution:  $x(t) = (A_0 + A_1t)e^{-\beta t}$ .

Initial conditions:  $A_0 = x_0, \quad A_1 = \dot{x}_0 + \beta x_0$ .

**Underdamped motion:**  $\omega_1 \equiv \sqrt{\omega_0^2 - \beta^2} > 0$

Linearly independent solutions:  $e^{r_+t}, e^{r_-t}$ .

General solution:  $x(t) = (A \cos \omega_1 t + B \sin \omega_1 t) e^{-\beta t} = D \cos(\omega_1 t - \delta) e^{-\beta t}$ .

$$D = \sqrt{A^2 + B^2}, \quad \delta = \arctan(B/A).$$

Initial conditions:  $A = x_0, \quad B = (\dot{x}_0 + \beta x_0)/\omega_1$ .

The dissipative force,  $-\gamma\dot{x}$ , effectively represents a coupling of one low-frequency oscillator to many high-frequency oscillators.