

# Hamilton's Characteristic Function [mln97]

Two distinct ways of solving the Hamilton-Jacobi equation become available when the Hamiltonian does not explicitly depend on time.

If  $H(q, p) = E = \text{const.}$  then  $\frac{\partial S}{\partial t} = -E = \text{const.}$

Set  $S(q, P, t) = W(q, P) - Et.$

Hamilton's characteristic function:  $W(q_1, \dots, q_n; P_1, \dots, P_n).$

## Method #1:

- Solve the Hamilton-Jacobi equation  $H\left(q, \frac{\partial S}{\partial q}\right) + \frac{\partial S}{\partial t} = 0.$
- Proceed as in [mln96] but use  $S(q, P, t) = W(q, P) - Et.$
- One of the integration constants is reserved:  $P_1 = E.$

## Method #2:

- Solve the Hamilton-Jacobi equation  $H\left(q, \frac{\partial W}{\partial q}\right) - E = 0.$
- $W(q, P)$  is a  $F_2$ -type generating function of a canonical transformation to action-angle coordinates with  $P_1 = K(P) = E.$
- Canonical Equations:  $\dot{Q}_j = \frac{\partial K}{\partial P_j} = \delta_{j1}, \quad \dot{P}_j = -\frac{\partial K}{\partial Q_j} = 0.$
- Solution:  $P_j = \text{const.}, \quad Q_j = t\delta_{j1} + Q_j^{(0)}.$
- Transformation to original canonical coordinates:

$$Q_j = \frac{\partial}{\partial P_j} W(q, P), \quad p_j = \frac{\partial}{\partial q_j} W(q, P).$$

$$\Rightarrow q_j = q_j(Q^{(0)}, P, t), \quad p_j = p_j(Q^{(0)}, P, t).$$