

# Classical Hamiltonian system [tln45]

Consider an autonomous classical dynamical system with  $3N$  degrees of freedom (e.g.  $N$  particles in a 3D box with reflecting walls). The dynamics is fully described by  $6N$  independent variables, e.g. by a set of *canonical coordinates*  $q_1, \dots, q_{3N}; p_1, \dots, p_{3N}$ .

The time evolution of these coordinates is specified by a *Hamiltonian function*  $H(q_1, \dots, q_{3N}; p_1, \dots, p_{3N})$  and determined by the *canonical equations*:

$$\dot{q}_i = \frac{\partial H}{\partial p_i}, \quad \dot{p}_i = -\frac{\partial H}{\partial q_i}; \quad i = 1, \dots, 3N$$

The time evolution of an arbitrary dynamical variable  $f(q_1, \dots, q_{3N}; p_1, \dots, p_{3N})$  is determined by *Hamilton's equation of motion*:

$$\frac{df}{dt} = \sum_{i=1}^{3N} \left( \frac{\partial f}{\partial q_i} \dot{q}_i + \frac{\partial f}{\partial p_i} \dot{p}_i \right) = \sum_{i=1}^{3N} \left( \frac{\partial f}{\partial q_i} \frac{\partial H}{\partial p_i} - \frac{\partial f}{\partial p_i} \frac{\partial H}{\partial q_i} \right) \equiv \{f, H\}.$$

Conserved quantity:  $\frac{df}{dt} = 0 \Leftrightarrow \{f, H\} = 0$ .

Energy conservation is guaranteed:  $\frac{dH}{dt} = 0$  because  $\{H, H\} = 0$ .

The microstate of the system is specified by one point in the  $6N$ -dimensional *phase space* ( $\Gamma$ -space):  $\mathbf{X} \equiv (q_1, \dots, q_{3N}; p_1, \dots, p_{3N})$ . As time evolves, this point traces a trajectory through  $\Gamma$ -space.

The conservation law  $H(q_1, \dots, q_{3N}; p_1, \dots, p_{3N}) = \text{const}$  confines the motion of any phase point to a  $6N - 1$ -dimensional hypersurface in  $\Gamma$ -space. Other conservation laws, provided they exist, will further reduce the dimensionality of the manifold to which phase-space trajectories are confined.

Note: Within the framework of kinetic theory, the microstate of the same system was described by  $N$  points in the 6D space spanned the position and velocity coordinates of a single particle,  $(x, y, z; v_x, v_y, v_z)$ .

Our knowledge of the instantaneous microstate of the system is expressed by a probability density  $\rho(\mathbf{X}, t)$  in  $\Gamma$ -space.

Normalization:  $\int_{\Gamma} d^{6N} X \rho(\mathbf{X}, t) = 1$ .

Instantaneous expectation value:  $\langle f \rangle = \int_{\Gamma} d^{6N} X f(\mathbf{X}) \rho(\mathbf{X}, t)$ .

Maximum knowledge about microstate realized for  $\rho(\mathbf{X}, 0) = \delta(\mathbf{X} - \mathbf{X}_0)$ .