

## Markovian or Non-Markovian II [nl53]

Consider a dilute classical gas, i.e. a physical ensemble of free massive particles moving in a box. The particles move with constant velocity between collisions. The average time between collisions is  $\tau_c$ . Here we focus on the motion of the particles in  $x$ -direction.

**Short time intervals:**  $t \ll \tau_c$  (no collisions during any time interval)

(i) Probability distribution of two-component random variable  $[x, \dot{x}]$ :

$$P([x_1, \dot{x}_1], t_1 | [x_0, \dot{x}_0], t_0) = \delta(\dot{x}_1 - \dot{x}_0) \delta(x_1 - x_0 - \dot{x}_0(t_1 - t_0)).$$

The motion is deterministic. The conditional probability distribution is sharp. The process thus described is Markovian. Any additional condition  $[x_{-1}, \dot{x}_{-1}]$  associated with a prior time  $t_{-1}$  is redundant.

(ii) Probability distribution of one-component random variable  $x$ :

(a) If we insist on a Markovian description, by means of the conditional probability distribution,

$$P_1(x_1, t_1 | x_0, t_0),$$

we obtain a broad distribution even though the process is deterministic.

(b) If we insist on a sharp distribution we must choose a non-Markovian description, by means of the probability distribution with two conditions,

$$P_2(x_1, t_1 | x_0, t_0; x_{-1}, t_{-1}).$$

Any further condition  $x_{-2}$  associated with a prior time  $t_{-2}$  is again redundant.

The contraction of the level of description from  $[x, \dot{x}]$  as in (i) to  $x$  as in (ii) of one and the same deterministic time evolution shifts information about the process into memory (cf. [nl15]).

**Long time intervals:**  $t \gg \tau_c$  (many collisions during every time interval)

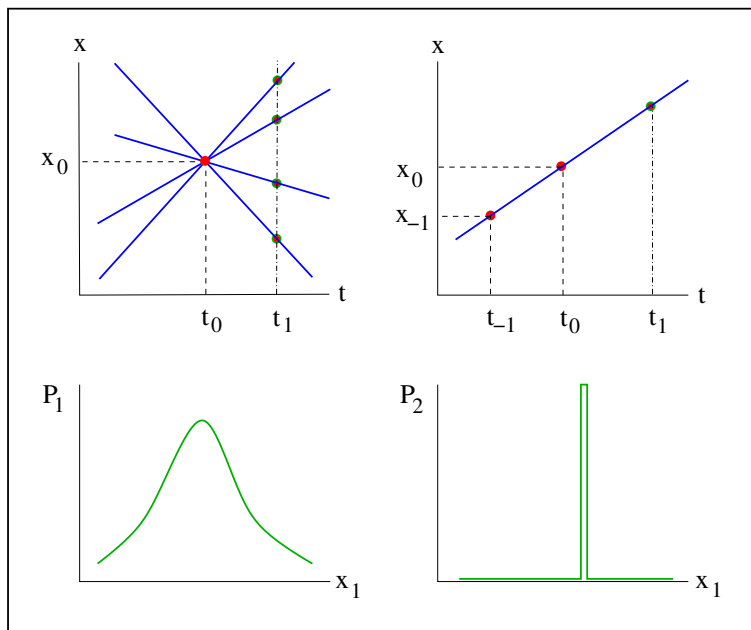
(iii) Markov process  $P_1(x_1, t_1 | x_0, t_0)$  is probabilistic (not deterministic).

(iv) Non-Markov process  $P_2(x_1, t_1 | x_0, t_0; x_{-1}, t_{-1})$  is also probabilistic.

Both conditional probability distributions are broad. The second condition narrows  $P_2$  down relative to  $P_1$  if  $t_0 - t_{-1}$  is short. With increasing  $t_0 - t_{-1}$  the effect of the second condition fades away.

[Illustrations on next page]

**Short time intervals:**  $t \ll \tau_c$  (no collisions during any time interval)



**Long time intervals:**  $t \gg \tau_c$  (many collisions during every time interval)

