$$|\psi(t)\rangle = \sum_{k=0}^{\infty} D_k(t)|f_k\rangle.$$
 (1)

Step #1:

- Hamiltonian:  $\bar{\mathcal{H}} \doteq \mathcal{H} E_0$  (generator of new directions).
- Ground state:  $|\phi_0\rangle$ .
- Dynamical variable of interest: A.
- Orthogonal basis,  $|f_0\rangle, |f_1\rangle, \ldots$ , with initial condition,  $|f_0\rangle = A|\phi_0\rangle$ .

Recurrence relations for basis vectors:

$$|f_{k+1}\rangle = \bar{\mathcal{H}}|f_k\rangle - a_k|f_k\rangle - b_k^2|f_{k-1}\rangle, \quad k = 0, 1, 2, \dots$$
 (2a)

$$a_k = \frac{\langle f_k | \bar{\mathcal{H}} | f_k \rangle}{\langle f_k | f_k \rangle}, \quad b_k^2 = \frac{\langle f_k | f_k \rangle}{\langle f_{k-1} | f_{k-1} \rangle}.$$
 (2b)

Conditions:  $|f_{-1}\rangle \doteq 0$ ,  $|f_0\rangle \doteq A|\phi_0\rangle$ ,  $b_0 \doteq 0$ .

First three iterations spelled out in [nln91].

Step #2: (setting  $\hbar = 1$ )

- Time-dependent coefficients of basis vectors:  $D_k(t)$ .
- Substitute (1) into eq. of motion from [nln81]:  $i\frac{d}{dt}|\psi(t)\rangle = \bar{\mathcal{H}}|\psi(t)\rangle$ .
- d/dt acts on  $D_k(t)$  and  $\bar{\mathcal{H}}$  on  $|f_k\rangle$ .

Comparison of coefficients in

$$i\sum_{k=0}^{\infty} \dot{D}_k(t)|f_k\rangle = \sum_{k=0}^{\infty} D_k(t) \left[ \left| \underbrace{f_{k+1} + a_k|f_k\rangle + b_k^2|f_{k-1}\rangle}_{\widehat{\mathcal{H}}|f_k\rangle} \right]$$
(3)

yields set of coupled, linear, first-order ODEs for functions  $D_k(t)$ :

$$i\dot{D}_k(t) = D_{k-1}(t) + a_k D_k(t) + b_k^2 D_{k+1}(t), \quad k = 0, 1, 2, \dots$$
 (4)

Conditions:  $D_{-1}(t) \equiv 0$ ,  $D_k(0) = \delta_{k,0}$ .

Normalized correlation function:

$$D_0(t) = \frac{\langle f_0 | \psi(t) \rangle}{\langle f_0 | f_0 \rangle} = \frac{\langle \phi_0 | A(0) A(-t) | \phi_0 \rangle}{\langle \phi_0 | A(0) A(0) | \phi_0} = \frac{\tilde{S}(t)}{\tilde{S}(0)} \doteq \tilde{S}_0(t).$$
 (5)