

Canonical Transformations [mln89]

Canonical transformations $(q; p) \rightarrow (Q; P)$ operate in phase space.

Notation: $(q; p) \equiv (q_1, \dots, q_n; p_1, \dots, p_n)$ etc.

Not every transformation $q_i = q_i(Q; P; t)$, $p_i = p_i(Q; P; t)$ preserves the structure of the canonical equations.

Canonicity of transformation $(q; p) \rightarrow (Q; P)$ hinges on relation between Hamiltonians $H(q; p; t)$ and $K(Q; P; t)$ such that

$$\dot{q}_i = \frac{\partial H}{\partial p_i}, \quad \dot{p}_i = -\frac{\partial H}{\partial q_i} \quad \Rightarrow \quad \dot{Q}_i = \frac{\partial K}{\partial P_i}, \quad \dot{P}_i = -\frac{\partial K}{\partial Q_i}.$$

Canonicity enforced via modified Hamilton's principle [mln83]:

$$\begin{aligned} \delta \int_{t_1}^{t_2} dt \left[\sum_j p_j \dot{q}_j - H(q; p; t) \right] &= \delta \int_{t_1}^{t_2} dt \left[\sum_j P_j \dot{Q}_j - K(Q; P; t) \right] = 0. \\ \Rightarrow \sum_j p_j \dot{q}_j - H(q; p; t) &= \sum_j P_j \dot{Q}_j - K(Q; P; t) + \frac{d}{dt} F_1(q; Q; t). \end{aligned}$$

Total time derivative of F_1 has vanishing variation:

$$\delta \int_{t_1}^{t_2} dt \frac{dF_1}{dt} = \left[\delta F_1 \right]_{t_1}^{t_2} = 0.$$

Generating functions are not unique. They all depend on n old and n new coordinates. Different generating functions for the same canonical transformation are related to each other.

The four basic types of generating functions are

$$\begin{aligned} F_1(q; Q; t) &= F_2(q; P; t) - \sum_j P_j Q_j \\ &= F_3(p; Q; t) + \sum_j p_j q_j \\ &= F_4(p; P; t) - \sum_j P_j Q_j + \sum_j p_j q_j. \end{aligned}$$

Each generating function has a specific mix of independent variables: n old coordinates and n new coordinates.

Implementation of canonical transformation specified by $F_1(q; Q; t)$:

$$\begin{aligned} \frac{d}{dt} F_1(q; Q; t) &= \sum_j (p_j \dot{q}_j - P_j \dot{Q}_j) - [H(q; p; t) - K(Q; P; t)] . \\ \Rightarrow \sum_j \left(\frac{\partial F_1}{\partial q_j} dq_j + \frac{\partial F_1}{\partial Q_j} dQ_j \right) + \frac{\partial F_1}{\partial t} dt &= \sum_j (p_j dq_j - P_j dQ_j) \\ &\quad - [H(q; p; t) - K(Q; P; t)] dt . \end{aligned}$$

Comparison of coefficients yields

$$p_j = \frac{\partial F_1}{\partial q_j}, \quad P_j = -\frac{\partial F_1}{\partial Q_j}, \quad K - H = \frac{\partial F_1}{\partial t}.$$

Transformation relations:

- Invert relations $P_j(q; Q; t)$ into $q_j(Q; P; t)$.
- Combine relations $p_j(q; Q; t)$ with $q_j(Q; P; t)$ to get $p_j(Q; P; t)$.

Transformed Hamiltonian:

- $K(Q; P; t) = H(q; p; t) + \frac{\partial}{\partial t} F_1(q; Q; t)$.

generating function	transformation of coordinates	transformation of Hamiltonian
$F_1(q, Q, t)$	$p_j = \frac{\partial F_1}{\partial q_j} \quad P_j = -\frac{\partial F_1}{\partial Q_j}$	$K = H + \frac{\partial F_1}{\partial t}$
$F_2(q, P, t)$	$p_j = \frac{\partial F_2}{\partial q_j} \quad Q_j = \frac{\partial F_2}{\partial P_j}$	$K = H + \frac{\partial F_2}{\partial t}$
$F_3(p, Q, t)$	$q_j = -\frac{\partial F_3}{\partial p_j} \quad P_j = -\frac{\partial F_3}{\partial Q_j}$	$K = H + \frac{\partial F_3}{\partial t}$
$F_4(p, P, t)$	$q_j = -\frac{\partial F_4}{\partial p_j} \quad Q_j = \frac{\partial F_4}{\partial P_j}$	$K = H + \frac{\partial F_4}{\partial t}$